IISTALLATION OPERATION \& MAINTENANCE


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## INTRODUCTION

The BK2900 flow monitor incorporates state-of-the-art, digital signal processing technology, designed to provide exceptional flexibility at a very affordable price. Though designed for use with Kimray flow sensors, this monitor can be used with almost any flow sensor producing a low amplitude AC output or contact closure signal.


Figure 24: BK2900 Flow monitor (NEMA 4X)

This monitor can accept low-level frequency input signals typically found in turbine flow sensors. The output signal for these types of sensors is a frequency proportional to the rate of flow. The BK2900 monitor uses the frequency information to calculate flow rate and total flow. Through the use of the programming buttons, you can select rate units, total units and unit time intervals among other functions. All BK2900 flow monitors come pre-configured from the factory, when ordered with a Kimray flow sensor. If required, the monitor can easily be re-configured in the field. Finally, you can choose between simultaneously showing rate and total, or alternating between rate and grand total.
The package is a polycarbonate NEMA 4X enclosure.

## SCOPE OF THIS MANUAL

This manual is intended to help you get the BK2900 flow monitor up and running quickly.

## IMPORTANT

Read this manual carefully before attempting any installation or operation. Keep the manual accessible for future reference.

## UNPACKING AND INSPECTION

Upon opening the shipping container, visually inspect the product and applicable accessories for any physical damage such as scratches, loose or broken parts, or any other sign of damage that may have occurred during shipment.
NOTE: If damage is found, request an inspection by the carrier's agent within 48 hours of delivery and file a claim with the carrier. A claim for equipment damage in transit is the sole responsibility of the purchaser.

## SAFETY

## Terminology and Symbols

## ADANGER

$\triangle$ WARNING

## ACAUTION

## Considerations

The installation of the BK2900 monitor must comply with all applicable federal, state, and local rules, regulations, and codes.

## AWARNING

EXPLOSION HAZARD - SUBSTITUTION OF COMPONENTS MAY IMPAIR SUITABILITY FOR CLASS I, DIVISION 2.

## $\triangle$ AVERTISSMENT

risque d'explosion - La substitution de composants peut rendre cematériel inaccceptable pour les EMPLACEMENTS DE CLASSE I, DIVISION 2.

## AWARNING

DO NOT CONNECT OR DISCONNECT EITHER POWER OR OUTPUTS UNLESS THE AREA IS KNOWN TO BE NONHAZARDOUS.

## ! AVERTISSMENT

RISQUE D'EXPLOSION. NE PAS DÉBRANCHER TANT QUE LE CIRCUIT EST SOUSTENSION, À MOINS QU'LL NE S'AGISSE D'UN EMPLACEMENT NON DANGEREUX.

## IMPORTANT

Not following instructions properly may impair safety of equipment and/or personnel.

## Electrical Symbols

| Function | Direct <br> Current | Alternating <br> Current | Earth <br> (Ground) | Protective <br> Ground | Chassis <br> Ground |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Symbol | $-\ldots-$ |  |  |  |  |

## INSTALLATION

## Connecting the BK2900 Monitor to a Frequency Output Device

The BK2900 monitor has two jumpers for setting the type of signal and the minimum amplitude of the signal that it accepts. First, establish the type of output provided by the flow sensor. The outputs almost always fall into one of two types.

- Type 1 is the unaltered frequency signal coming from an un-amplified magnetic pickup. This signal is normally a sine wave in appearance, and the amplitude of the waveform varies with the flow. Small turbines have comparatively small rotating masses so they produce a smaller amplitude waveform and higher frequencies than larger turbine sensors.
- Type 2 is the frequency signal from the transducer is amplified, wave shaped or both to produce a waveform of a specified type and amplitude. Most amplified transducers output a square wave shape at one of many standard amplitudes. For example, a popular amplified output is a 10V DC square wave.
If the flow sensors output signal is type 1 , you must also determine the minimum amplitude of the frequency output. The BK2900 monitor has a high or low signal sensitivity setting. Use the high signal sensitivity ( 30 mV ) with low amplitude (usually small) turbine flow sensors. Use the low signal sensitivity setting ( 60 mV ) for larger turbines and amplified transducers (see Figure 2).
NOTE: Use the high signal sensitivity setting where the minimum signal amplitude is below 60 mV . Setting the sensitivity higher than necessary may allow noise interference.


Figure 1: Input jumper settings (NEMA 4X)
When the type of waveform and input signal level (amplitude) are determined, set the jumpers on the BK2900 monitor circuit board.
For typical variable reluctance magnetic pickups, set the waveform selection jumper for Mag. Determine the setting for the input level by looking at the magnetic pickup specifications. If the minimum amplitude at the minimum rated flow is greater than 60 mV , use the low signal sensitivity jumper position (see Figure 2).
If the minimum signal level is below 60 mV , use the high signal sensitivity jumper position.


Figure 2: Typical magnetic pickup connection (NEMA 4X)
For amplified input signals, set the input jumper to Pulse and the signal jumper to Low (see Figure 4).
NOTE: Amplified magnetic pickups require an external power source. The BK2900 monitor does not supply power to an amplified pickup.


Figure 3: Typical amplified pickup connection (NEMA 4X)

## POWER CONNECTIONS

## Standard

The power supply used in the BK2900 monitor is an internal lithium 3.6V DC D cell that powers the monitor for about six years when no outputs are used. The monitor can also get power from a $4 \ldots 20 \mathrm{~mA}$ current loop (see Figure 5). If the current loop is used, a sensing circuit within the monitor detects the presence of the current loop and disconnects the battery from the circuit.


Figure 4: Loop power connections (NEMA 4X)

## OPERATING THE MONITOR

## Buttons



Figure 5: Keypad detail

| MENU | Switches to PROGRAM mode, press and hold for three seconds to enter EXTENDED <br> PROGRAMMING mode, and is used in reset process |
| ---: | ---: | :--- |
| $\mathbf{U R}$ | Scrolls forward through the parameter choices, increments numeric variables and <br> increases display contrast in RUN mode |
| RIGHT | Scrolls backward through the parameter choices, moves the active digit to the right and <br> decreases display contrast in RUN mode |
|  | Saves programming information, advances to the next programming parameter, and is <br> used in the reset process |

## Special Functions

| MENU + ENTER | Simultaneously press and hold to reset the current totalizer |
| :--- | :--- |
| UP + RIGHT | Simultaneously press and hold to show the firmware version number, then the grand total |

## Modes of Operation

The monitor has three modes of operation-Run, Programming and Extended Programming modes.


Figure 6: Display annunciators

| RUN | Normal operating mode |
| :--- | :--- |
| PROGRAM | Program variables into the display |
| EXTENDED PROGRAM | Program advanced variables into the display |
| TEST | Diagnostic tool to show input frequency and totalizer counts |

If your monitor was ordered with a Kimray flow meter, the two components ship from the factory configured as a set. If the monitor is a replacement, the turbine's K-factor changed or the monitor is used with some other pulse generating device, you must program it.

## Programming Using Frequency Output Turbine Flow Meters

Each Kimray turbine flow meter is shipped with either a K-factor value or frequency data. If frequency data is provided, the data must be converted to a K-factor before programming the monitor. K-factor information, when supplied, can usually be found on the neck of the flow meter or stamped on the flow meter body. The K-factor represents the number of pulses per unit of volume (see K-Factors Explained on page 28). The K-factor is required to program the monitor.

## Enter Programming Mode

To access the Programming mode, momentarily press and then release MENU. The monitor displays Fluid. To access the Extended Programming mode, press and hold MENU until Fluid is displayed. To return to Run mode, press MENU.


Figure 7: Programming mode display

## PROGRAMMING

The following programming assumes the meter is set for liquid. Parameters for gaseous fluids can be found in Gas on page 21.
NOTE: All of the following parameters appear in Extended Programming mode. Parameters with an asterisk (*) appear in Programming mode as well.

## Liquid

## Select Fluid*

At the Fluid prompt, press ENTER to view the current fluid type. If the current fluid type is correct, press ENTER to advance to the next parameter. To change the fluid type, press UP or RIGHT to switch between Liquid or Gas. Press ENTER to save and advance to the Meter parameter.

NOTE: The fluid selection choice affects which menu choices are available. See Menu Maps on page 24 for details.

## Select Meter Size*

At the Meter prompt, press ENTER to display the current meter size. If the current meter size is correct, press ENTER to advance to the next parameter. To change the meter size, press UP or RIGHT to scroll to the correct meter size. Press ENTER to advance to the next parameter.
NOTE: The meter size selection refers to the bore of the meter and not the connections size. For a listing of the Kimray turbine bore sizes, see the default K-factor table in Default K-Factor Values on page 22.
NOTE: In Programming mode, the monitor advances to the KFacUnit parameter. See Select Meter's K-Factor Unit* on page 13.

## Select Display Function

The BK2900 monitor has three display settings, Flow, Grand Total and Test.
Flow
Use the Flow setting for normal operation of the monitor. In this mode, the display shows both the instantaneous flow rate and current total simultaneously. See Figure 9.


Figure 8: Instantaneous flow rate and current total

## Grand Total

The Flow-GT setting forces the meter to alternate between the instantaneous flow and the grand total with roll-over counts. See Figure 10.
The grand total is the accumulation of all the fluid that has gone through the meter since the last time the grand total was cleared. This totalizer is in addition to the current total totalizer on the display and is always enabled.
In addition, the grand total screen displays the number of times the grand total has reached its maximum count $(9,999,999)$ and rolled over to zero.


Figure 9: Grand total

## Test

The Test setting places the monitor into a special diagnostic mode that shows the current input frequency and the accumulated input counts. Figure 11 shows the layout for test mode values. The Test mode makes it possible for you to see the frequency input the monitor is measuring and is very useful in troubleshooting and noise detection.


Figure 10: Test mode screen
At the Display prompt, press ENTER to view the current display setting. If the current display setting is correct, press ENTER to advance to the next parameter. To change the display setting, press UP or RIGHT to scroll through the display options. Press ENTER to save and advance to the KFacUnit parameter.

## Select Meter's K-Factor Unit*

At the KFacUnt prompt, press ENTER. The display shows the current K-factor unit. If the current selection is correct, press ENTER to advance to the next parameter. To change the K-factor unit, press UP or RIGHT to scroll to the correct unit, the units should match the units that the meter was calibrated in. Press ENTER to save and advance to the KFactor parameter.

## Enter Meter's K-Factor*

NOTE: The K-factor supplied with your meter, or calculated from calibration data, is needed to complete this step.
At the KFactor prompt, press ENTER. The most significant digit in the K-factor flashes. If the current K-factor is correct, press ENTER to advance to the next parameter. To change the K-factor, press UP to increment the digit until it matches the meter's first K-factor digit. Press RIGHT to advance to the next digit. Repeat this process until all K-factor digits have been entered. Press ENTER to save the K-factor and advance to the RateInt parameter.
NOTE: The number of digits available before and after the decimal point is determined by the bore size of the flow sensor being used. The largest K-factors are associated with the smallest bore sizes. The maximum allowable K-factor is 99999.9. The minimum must be at least 1.000. If an out of range number is entered, the display flashes Limit and refuses the entry.

## Select Rate Interval*

At the Ratelnt prompt, press ENTER. The monitor flashes the current time interval. If the current selection is correct, press ENTER to advance to the next parameter. To change to an alternate time interval, press UP or RIGHT to scroll to the required time interval. Press ENTER to save and advance to the RateUnt parameter.

## Select Flow Rate Units*

At the RateUnt prompt, press ENTER. The monitor flashes the current rate unit. If the current selection is correct, press ENTER to advance to the next parameter. To change to an alternate unit, press UP or RIGHT to scroll to the required rate unit and press ENTER to save and advance to the Tot/Unt parameter.

## Select Total Units of Measure*

At the TotlUnt prompt, press ENTER. The monitor flashes the current total units. If the current selection is correct, press ENTER to advance to the next parameter. To change to an alternate unit, press UP or RIGHT to scroll to the required totalization unit. Press ENTER to save and advance to the TotIMul parameter.

## Select Total Multiplier*

This parameter displays the accumulated flow total in multiples of 10 . For example, if the optimum totalization unit is 1000 gallons, the unit total display increments by one digit for every 1000 gallons monitored. In Run mode, at 1000 gallons the total monitor reads 1, at 3000 gallons, the total display reads 3 . This feature eliminates having to look at a total, count the digits, and mentally insert commas for each 1000 multiple.
At the Tot/Mul prompt, press ENTER. The monitor shows the current total multiplier. If the selection is correct, press ENTER to advance to the next parameter. To change to an alternate multiplier, press UP or RIGHT to scroll to the required multiplier unit and press ENTER to and advance to the next parameter.
NOTE: If the RateUnt or TotIUnt parameter has been set to pounds or kilograms, the monitor advances to the Spec Gr parameter. At any other setting, the monitor advances to PulsOut in Programming mode. See Totalizer Pulse Output* on page 16.

## Enter Specific Gravity Value*

Mass readings in the BK2900 monitor are not temperature or pressure compensated so it is best to enter the specific gravity of the fluid as close to the system running temperature as possible. As liquids are essentially incompressible, pressure compensation is not necessary for liquids.
At the Spec Gr prompt, press ENTER. The most significant digit of the current specific gravity flashes. If the current specific gravity is correct, press ENTER to advance to the next parameter. To change to an alternate specific gravity, press UP to increment the flashing digit until you reach the first digit of the new specific gravity. Press RIGHT to move to the next digit. When all digits have been entered, press ENTER to save and advance to the next parameter.
NOTE: If Gas was chosen as the fluid, see Gas on page 21 and follow the directions for the gas parameters.
In Programming mode, the monitor advances to the PulsOut parameter, see Totalizer Pulse Output* on page 16.

## Enter a Scale Factor

The scale factor is used to force a global span change. For example, in Run mode the display is reading a consistent three percent below the expected values at all flow rates. Rather than changing the K-factor and linearization parameters individually, the scale factor can be set to 1.03 to correct the readings. The range of scale factors is from $0.10 \ldots 5.00$. The default scale factor is 1.00 .

At the Scale F prompt, press ENTER. The first digit of the existing scale factor flashes. If the current selection is correct, press ENTER to advance to the next parameter. To change to an alternate scale factor, press UP to increment the display digit until it matches the first digit of the new scale factor. Press RIGHT to advance to the next digit. Repeat for all digits. Press ENTER to save and advance to the SetTotl parameter.
NOTE: If the number you enter is out of range, the display flashes Limit and refuses the entry.

## Preset Total

The preset total parameter sets the totalizer to a predetermined amount. The preset can have seven digits up to 8,888,888.
At the SetTot/ prompt, press ENTER. The monitor displays the current set total. If the set total is correct, press RIGHT to advance to the next parameter. To change the set total, press ENTER again. The first digit of the current preset total flashes. Press UP to increment the display digit until it matches the first digit of the correct preset. Press RIGHT to advance to the next digit. Repeat for all digits. Press ENTER to save and advance to the Cutoff parameter.

NOTE: If the number you enter is out of range, the display flashes Limit and refuses the entry.

## Low Flow Cutoff

The flow cutoff shows low flow rates (that can be present when pumps are off and valves are closed) as zero flow on the flow monitor. A typical value would be about five percent of the flow sensor's maximum flow.
Enter the low flow cutoff as an actual flow value. For example, if the maximum flow rate for the flow sensor was 100 gpm , set the low flow cutoff value to 5.0.
At the Cutoff prompt, press ENTER. The first digit of the current low flow cutoff flashes. If the current selection is correct, press ENTER to advance to the next parameter. To change the low flow cutoff, press UP to increment the display digit until it matches the first digit of the new low flow cutoff value. Press RIGHT to advance to the next digit. Repeat for all digits. Press
ENTER to save and advance to the Damping parameter.
NOTE: If the number you enter is out of range, the display flashes Limit and refuses the entry.
NOTE: If the fluid being measured is set to Gas, the monitor advances to Op Pres in Extended Programming mode. See Gas on page 21.

## Damping Factor

The damping factor is increased to enhance the stability of the flow readings. Damping values are decreased to allow the monitor to react faster to changing values of flow. This parameter can be any value between $0 \ldots . .99 \%$, with 0 being the default.

At the Damping prompt, press ENTER. The most significant digit of the current setting flashes. If the current selection is correct, press ENTER to advance to the next parameter. To change the damping value, press UP to increment the display digit until it matches the new damping value. Press RIGHT to advance to the next digit. Press ENTER to save and advance to the PulsOut parameter.

## Totalizer Pulse Output*

The PulsOut parameter can be enabled or disabled. When enabled, the output generates a fixed width 30 mS duration, pulse every time the least significant digit of the totalizer increments. The amplitude of the pulse is dependent on the voltage level of the supply connected to the pulse output and is limited to a maximum 28 V DC.
The BK2900 monitor provides two types of totalizer pulses. The basic open drain FET output, Figure 12, provides a ground referenced output pulse that swings between about 0.7 V DC and $\mathrm{V}_{\mathrm{cc}}$.


Figure 11: Open drain connections (NEMA 4X)
The isolated pulse output (ISO), Figure 13, is an open collector output with the emitter of the transistor connected to the negative output terminal and is not referenced to ground. This output is optically isolated from the input signal for systems that require a totally isolated output pulse.


Figure 12: Opto-isolated open collector connections (NEMA 4X)
Both outputs have a maximum current capacity of 100 mA and require a pullup resistor. The value of the pullup resistor is dependent on the supply voltage and the maximum current required by the load device.

## Flow at $\mathbf{2 0} \mathbf{~ m A}$

This setting normally represents the maximum rate of the flow sensor connected to the display, but other entries are possible. At the $\mathrm{Fl}=20 \mathrm{~mA}$ prompt, press ENTER. The first digit of the current setting flashes. If the current setting is correct, press ENTER to advance to the next parameter. If the current setting requires a change, press UP to increment the display digit until it matches the first digit of the required maximum flow value. Press RIGHT to advance to the next digit. Repeat for all of the maximum flow at 20 mA digits. Press ENTER to save and advance to the 4-20Cal parameter.
In Programming mode, the monitor advances to the CIr G-T parameter. See Clear Grand Total on page 21.

## 4... 20 mA Calibration

This setting allows the fine adjustment of the Digital to Analog Converter (DAC) that controls $4 \ldots 20 \mathrm{~mA}$ output. The $4 \ldots 20 \mathrm{~mA}$ output is calibrated at the factory and under most circumstances does not need to be adjusted. If the output needs to be adjusted for any reason the $4 \ldots 20 \mathrm{~mA}$ calibration procedure is used.
At the 4-20Cal prompt, press ENTER. The monitor displays No. If you do not need to complete the $4 \ldots 20$ calibration, press ENTER to advance to the Linear parameter. See Linearization on page 18. To complete the $4 \ldots .20$ calibration, press UP or RIGHT to change the display to Yes. Press ENTER to advance to the $4 m A$ Out parameter.
The DAC used in the BK2900 monitor is an twelve bit device. The valid entries are 0...4095.


Figure 13: $4 . . .20 \mathrm{~mA}$ calibration setup

## 4 mA Adjustment

To set the 4 mA value, connect an ammeter in series with the loop power supply as shown in Figure 14. The 4 mA DAC setting is typically $35 \ldots 50$. At the $4 m A$ Out prompt, press UP to increase or RIGHT to decrease the current output while monitoring the ammeter. When a steady 4 mA reading is established on the ammeter, press ENTER on the monitor to save the output and advance to the 20 mAO ut parameter.

## 20 mA Adjustment

The 20 mA adjustment is performed using the same procedure as the 4 mA adjustment.

## 4... 20 mA Test

The $4 \ldots .20 \mathrm{~mA}$ test simulates the mA output values between $4 \ldots 20$ to check output tracking. At the 4-20 Test prompt the current output flashes. Press UP to increase the simulated mA output or RIGHT to decrease in increments of 1 mA . The ammeter should track the simulated mA output. If a $4 \ldots .20 \mathrm{~mA}$ test is not necessary, press ENTER to advance to the Linear parameter.

NOTE: Pressing ENTER when the monitor is in test mode exits the test mode and moves on to the next programming parameter.

## Linearization

To increase accuracy, linearize the monitor. The linearization function accepts a maximum of ten points and requires additional calibration data from the meter being used with the monitor. Typically, calibration information can be obtained in three, five and ten points from the flow meter's manufacturer. If linearization is not needed, press RIGHT to advance to the Modbus parameter. See Modbus on page 19. To complete linearization, press ENTER at the Linear prompt. The meter advances to the Lin Pts parameter.

## Number of Points

The Lin Pts value displays. If the number of points is set to 0 , linearization is disabled. Press ENTER. The most significant digit of the number of points entry begins to flash. The first number can be 1 or 0 only. Press UP to change the first digit. Press
RIGHT to move to the least significant digit.
NOTE: If the number you enter is out of range, the display flashes Limit and refuses the entry.
Press ENTER to advance to the Freq\#1 prompt.
NOTE: If the number of linear points is set to 1 the BK2900 monitor assumes you are entering the maximum frequency and coefficient. Further, the meter assumes that the implied first point is at a frequency of 0 Hz and a coefficient of 0 .

## Frequency

At the Freq\#1 prompt, press ENTER. The first digit of the first linear point's frequency input flashes. Press UP to increment the numerical values and RIGHT to change the position of the number being entered. When the frequency value input is complete, press ENTER to save and advance to the Coef\#1 parameter.

## Coefficient

The coefficient is the value applied to the nominal K-factor to correct it to the exact K-factor for that point. The coefficient is calculated by dividing the average (nominal) K-factor for that point by the actual K-factor for the flow meter.

$$
\text { Linear Coefficient }=\frac{\text { Nominal K-Factor }}{\text { Actual K-Factor }}
$$

At the Coef\#1 prompt, press ENTER. The first digit of the coefficient flashes. Press UP to increment the digit, and RIGHT to move to the next digit. When all digits have been entered, press ENTER to save and advance to the next frequency input. Continue entering pairs of frequency and coefficient points until all data has been entered. Press ENTER to save and advance to the Modbus parameter.
NOTE: The frequency values must be entered in ascending order. If a lower frequency value is entered after a higher value, the BK2900 monitor flashes Limit followed by the minimum frequency value acceptable to the display.

## Example:

The following is actual data taken from a one inch turbine flow sensor calibrated with water.

| Unit Under Test (UUT) Calibration Data Table In GPM |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Actual gpm | UUT Frequency | UUT Actual K-factor | (Hz x 60) <br> Nominal K | Linear Coefficient | Raw Error |
|  | Hz | Counts/US Gallon | GPM |  | \% Rate |
| 50.02 | 755.900 | 906.72 | 49.72 | 1.0060 | 0.59 |
| 28.12 | 426.000 | 908.96 | 28.02 | 1.0035 | 0.35 |
| 15.80 | 240.500 | 913.29 | 15.82 | 0.9987 | -0.13 |
| 8.88 | 135.800 | 917.57 | 8.93 | 0.9941 | -0.59 |
| 4.95 | 75.100 | 910.30 | 4.94 | 1.0020 | 0.20 |
| Nominal K (NK) |  | 912.144 |  | - | - |

Table 1: Sample linearization data
In this example, the linear coefficient has already been calculated by the calibration program so all that is required is to enter 5 into the number of linear points Lin Pts parameter and then enter, in order, the five frequency, linear coefficient data pairs.

## Modbus

The Modbus output parameter can be enabled or disabled. When enabled, communications with the BK2900 monitor are completed using the Modbus RTU protocol. See Modbus Interface on page 31 for additional information.
At the Modbus prompt, press ENTER. The current state of the Modbus output is shown. If the current state is correct, press ENTER to advance to the next parameter. To change the modbus setting, press UP or RIGHT to toggle between states. When the proper state displays, press ENTER to save and advance to the BusAddr parameter.

## Bus Address

If the Modbus output is enabled, you must choose a valid Modbus address. Every device communicating over the RS485 communications bus using the Modbus protocol must have a unique bus address. Address values range from $0 . . .127$ with 0 being the default.
At the BusAddr prompt, press ENTER. The first digit of the address flashes. If the current setting is correct, press ENTER to advance to the next parameter. To change the address, press UP to increment the display digit until it matches the first digit of the new bus address. Press RIGHT to advance to the next digit. Repeat for all digits of the address. Press ENTER to save the new address and advance to the Baud parameter.

## Baud

If Modbus is being used, all devices connected to the bus, must have the same baud rate setting. Baud is expressed as 'bits per second' and defines the data transmission speed of the network. The BK2900 monitor can be changed to use any of the following baud rates: 9600, 19200, 38400, 57600 and 115200 . See Modbus Interface on page 31 for additional information.
At the Baud prompt, press ENTER. The current state of the Baud rate is shown and defaults to 9600 . If the current state is correct, press ENTER to advance to the next parameter. To change the baud rate setting, press UP or RIGHT to scroll through the options. When the proper state displays, press ENTER to save and advance to the SetPt1 parameter.

## Set Points

Set points allow the meter to signal when a specific flow condition has been achieved. They are commonly used to indicate high or low flow conditions that need attention. The BK2900 monitor has two open collector outputs controlled by the set point function.
The set point transistors have the same current limitations and setup requirements as the totalizing pulse output transistors described previously (see Figure 14 on page 17 and Figure 15).
Both set point one and set point two are configured using the same procedures but the hysteresis and tripping conditions are independently set for each set point output.
NOTE: In most instances, the current capacity of an open collector transistor is not sufficient to operate old style counters that relied on relay contact closures. When used with basic counting circuits, a solid-state relay is needed.

## Set Point 1

The set point is the flow value at which the output transistor changes state. It is set using the same units as the rate units.


Figure 14: Set point output (NEMA 4X)

At the SetPt 1 prompt, press ENTER. The most significant digit of the current setting flashes. If the current setting is correct, press ENTER to advance to the next parameter. To change the current setting, press RIGHT to advance to the first digit of the required set point value. Press UP to increment the digit until it matches the first number of the required set point. Repeat for all the digits the set point. Press ENTER to save the new set point and advance to the HystSP1 parameter.

## Hysteresis 1

The hysteresis parameter modifies how the output transistor reacts around a set point and prevents an output from turning on and off rapidly when the programmed flow rate is at, or very near, the set point.
For example, a low flow alarm is set to activate when the flow falls below a pre-programmed point. When the flow is reduced to the set point, even small changes of flow above the set point turns the output off, disabling the alarm. Without hysteresis, if the flow rate fluctuates slightly above and below the set point, the output rapidly cycles between on and off states. See Figure 16. The hysteresis value is set using the same units as the rate units.
At the HystSP1 prompt, press ENTER. The most significant digit of the current setting flashes. If the current setting is correct, press ENTER to advance to the next parameter. To change the current setting, press RIGHT to advance to the first digit of the new hysteresis value. Press UP to increment the digit until it matches the first number of the new hysteresis. Repeat for all the digits of the hysteresis and then press ENTER to save and advance to the TripSP1 parameter.


Figure 15: Set point actions
NOTE: Neither the set point nor the hysteresis values are checked for compatibility with the meter size. Check the values to prevent the outputs from working unexpectedly.

## Trip SP 1

The trip parameter can be set for either High or Lo. When set to high, the open collector transistor stops conducting and sends the output high when the set point is reached. The output will not go low again until the flow rate falls below the set point minus the hysteresis value. When set to low, the open collector transistor starts conducting and sends the output low when the set point is reached. The output will not go high again until the flow rate exceeds the set point plus the hysteresis value.
For example, if the set point is 10 gpm , the hysteresis is set to 2 gpm and the trip set point is set to High (see Figure 17). When the flow goes above 10 gpm , the OC transistor stops conducting and the output goes high. The output stays high until the flow rate drops below 8 gpm , which is the set point ( 10 gpm ) minus the hysteresis ( 2 gpm ).


Figure 16: Set point example
At the TripSP1 prompt, press ENTER. The current tripping condition setting displays. If the current setting is correct, press ENTER to advance to the next parameter.
If the current setting requires a change, press UP or RIGHT to change to the alternate choice. Press ENTER to save and advance to the SetPt 2 parameter.
The SetPt 2, HystSP2 and TripSP2 parameters are set using the same procedures as the SetPt 1, HystSP1 and TripSP1 parameters. When these parameters have been entered, the monitor advances to the CIr G-T parameter.

## Clear Grand Total

At the CIr G-T prompt, press ENTER. The monitor displays No on the screen. To clear the grand total, press UP or RIGHT to change from No to Yes. Press ENTER to save and advance to the Passwd parameter.
The totalizer can also be reset using a hardware reset, as shown in the following diagrams or by pressing MENU and ENTER simultaneously.


Figure 17: NEMA 4X hardware reset

## Password

The password setting restricts access to the Programming and Extended Programming modes. Initially, the password is set to all zeros and any user can modify the paramter settings. To change the password, press ENTER at the Passwd prompt. The first digit flashes. Press UP to increment the digit and RIGHT to advance to the next digit. After entering all digits, press ENTER to store the password and advance to RST PSWD. The new password is now required to enter either programming mode. With this password set, any user is able to reset the stored totals on the monitor.

## Reset Password

The reset password parameter restricts resetting the totals on the monitor. The Password must also be set to restrict the total reset. Initially, the password is set to all zeros and any user can reset the stored totals on the monitor. To change the password, press ENTER at the RstPswd prompt. The first digit flashes. Press UP to increment the digit and RIGHT to advance to the next digit. After entering all digits, press ENTER to store the password and return to the Fluid parameter. The reset pasword is now required to reset the totals on the monitor.
NOTE: Entering a password in the Passwd screen and leaving the password blank in the RstPswd screen allows for total resets (not requiring a password), but restricts programming modification.

## Gas

## Operating Pressure

At the Op Pres prompt, press ENTER. The first digit of the current pressure setting flashes. If the current selection is correct, press ENTER to advance to the next parameter. To change the operating pressure, press UP to increment the digit until it matches the first digit of the correct pressure value. Press RIGHT to move to the next digit. When all the digits have been entered, press ENTER to save and advance to the Op Temp parameter.

## Operating Temperature

At the Op Temp prompt, press ENTER. The first digit of the current temperature setting flashes. If the current selection is correct, press ENTER to advance to the next parameter. To change the operating temperature, press UP to increment the digit until it matches the first digit of the correct pressure value. Press RIGHT to move to the next digit. When all the digits have been entered, press ENTER to save and advance to the next parameter.
In Programming mode the monitor advances to the PulsOut parameter, see Totalizer Pulse Output* on page 16.
In Extended Programming mode, the monitor advances to the Damping parameter, see Damping Factor on page 15.

## Return to Run Mode

After entering all parameters, press MENU. Saving displays on the menu, followed by a blank screen and then the firmware version number. The monitor then returns to Run mode.

## TROUBLESHOOTING GUIDE

| Trouble |  |  |
| :--- | :--- | :--- |
| No LCD <br> Display | Battery | Loop Power |
|  |  | Check battery voltage. Should be 3.6V DC. Replace if low or bad. |
|  | Check 4...20 mA input. Voltage must be within the minimum and maximum supply <br> voltage and capable of supplying enough current to run the display. The input voltage is <br> checked across, or in parallel with, the 4...20 mA terminals. Current is checked with the <br> ammeter in series with the 4...20 mA output. |  |
| Flow Rate Display Interprets | Check connection from meter pickup to display input terminals. <br> Check turbine meter rotor for debris. Rotor should spin freely. <br> Check programming of flow monitor. |  |
| Reading Constantly | This is usually an indication of external noise. Keep all AC wires separate from DC wires. <br> Check for large motors close to the meter pick-up. <br> Check for radio antenna in close proximity. <br> Try disconnecting the pick-up from the monitor pig tail. This should stop the noise. |  |
| Flow Rate Indicator Bounces | This usually indicates a weak signal. Replace pick-up and/or check all connections. <br> Examine K-factor. |  |

## DEFAULT K-FACTOR VALUES

| Liquids |  |  |  |
| :---: | :---: | :---: | :---: |
| Meter Bore Size | Default K-factor | Lower Limit | Upper Limit |
| 0.375 | 20,000 | 16,000 | 24,000 |
| 0.500 | 13,000 | 10,400 | 15,600 |
| 0.750 | 2750 | 2200 | 3300 |
| 0.875 | 2686 | 2148 | 3223 |
| 1.000 | 870.0 | 696.0 | 1044 |
| 1.500 | 330.0 | 264.0 | 396.0 |
| 2.000 | 52.0 | 41.6 | 62.0 |
| 3.000 | 57.0 | 45.6 | 68.0 |
| 4.000 | 29.0 | 23.2 | 35.0 |
| 6.000 | 7.0 | 5.6 | 8.0 |
| 8.000 | 3.0 | 2.4 | 4.0 |
| 10.000 | 1.6 | 1.3 | 2.0 |


| Gas |  |
| :---: | :---: |
| Meter Range | Default K-factor |
| Low | 325 |
| Medium | 125 |
| High | 80 |

## BATTERY REPLACEMENT

Battery powered monitors use a single 3.6 V DC, D size lithium battery. When replacement is necessary, use a clean, fresh battery for continued trouble-free operation.

| Replacement Batteries |  |
| :---: | :---: |
| Manufacturer | Part Number |
| Blancett | B300028 |
| Xeno | S11-0205-10-03 |
| Tadiran |  |
| Table 2: Replacement batteries |  |

1. Unscrew the two captive screws on the front panel to gain access to the battery.
2. Press the tab on the battery connector to release it from the circuit board.
3. Remove the old battery and replace it with new one.
4. Re-fasten the front panel.

NOTE: The battery is held in place with a wire-tie that will need to be cut and replaced (see Figure 19). The approval on the product requires the wire-tie.


Figure 18: NEMA 4X battery replacement

## MENU MAPS



Figure 19: Extended liquid


Figure 20: Liquid


Figure 21: Gas


Figure 22: Extended gas

## K-FACTORS EXPLAINED

The K-factor (with regard to flow) is the number of pulses that must be accumulated to equal a particular volume of fluid. You can think of each pulse as representing a small fraction of the totalizing unit.
An example is a K-factor of 1000 (pulses per gallon). This means that if you were counting pulses, when the count total reached 1000, you would have accumulated one gallon of liquid. Using the same reasoning, each individual pulse represents an accumulation of $1 / 1000$ of a gallon. This relationship is independent of the time it takes to accumulate the counts.
The frequency aspect of K-factors is a little more confusing because it also involves the flow rate. The same K-factor number, with a time frame added, can be converted into a flow rate. If you accumulated 1000 counts ( 1 gallon) in one minute, then your flow rate would be 1 gpm . The output frequency, in Hz , is found by dividing the number of counts (1000) by the number of seconds in a minute (60) to get the output frequency.
$1000 \div 60=16.6666 \mathrm{~Hz}$.
If you were looking at the pulse output on a frequency counter, an output frequency of 16.666 Hz would be equal to 1 gpm . If the frequency counter registered $33.333 \mathrm{~Hz}(2 \times 16.666 \mathrm{~Hz})$, then the flow rate would be 2 gpm .
Finally, if the flow rate is 2 gpm , then the accumulation of 1000 counts would take place in 30 seconds because the flow rate that the 1000 counts is accumulated, is twice as great.

## Calculating K-factors

Many styles of flow meters are capable of measuring flow in a wide range of pipe sizes. Because the pipe size and volumetric units the meter will be used on varies, it may not be possible to provide a discrete K-factor. In the event that a discrete K-factor is not supplied, then the velocity range of the meter is usually provided along with a maximum frequency output.
The most basic K-factor calculation requires that an accurate flow rate and the output frequency associated with that flow rate be known.

Example 1
Known values are:

| Frequency | $=$ | 700 Hz |
| :--- | :--- | :--- |
| Flow Rate | $=$ | 48 gpm |

$$
700 \mathrm{~Hz} \times 60 \mathrm{sec}=42,000 \text { pulses per min }
$$

$$
\text { K-factor }=\frac{42,000 \text { pulses per min }}{48 \mathrm{gpm}}=875 \text { pulses per gallon }
$$

Example 2
Known values are:

| Full Scale Flow Rate | $=$ | 85 gpm |
| :--- | :--- | :--- |
| Full Scale Output Frequency | $=$ | 650 Hz |

$$
\begin{aligned}
& 650 \mathrm{~Hz} \times 60 \mathrm{sec}=39,000 \text { pulses per min } \\
& \text { K-factor }=\frac{39,000 \text { pulses per min }}{85 \mathrm{gpm}}=458.82 \text { pulses per gallon }
\end{aligned}
$$

The calculation is a little more complex if the velocity is used because you first must convert the velocity into a volumetric flow rate to be able to compute a K-factor.
To convert a velocity into a volumetric flow, the velocity measurement and an accurate measurement of the inside diameter of the pipe must be known as well as one US gallon of liquid is equal to 231 cubic inches.

Example 3
Known values are:
Velocity $=\quad 4.3 \mathrm{ft} / \mathrm{sec}$
Inside Diameter of Pipe $=3.068$ in.
Find the area of the pipe cross section.

$$
\text { Area }=\pi r^{2}
$$

$$
\text { Area }=\pi\left(\frac{3.068}{2}\right)^{2}=\pi \times 2.35=7.39 \mathrm{in}^{2}
$$

Find the volume in one foot of travel.

$$
7.39 \mathrm{in}^{2} \times 12 \mathrm{in} .(1 \mathrm{ft})=\frac{88.71 \mathrm{in}^{2}}{\mathrm{ft}}
$$

What portion of a gallon does one foot of travel represent?

$$
\frac{88.71 \mathrm{in}^{3}}{231 \mathrm{in}^{3}}=0.384 \text { gallons }
$$

So for every foot of fluid travel 0.384 gallons will pass.
What is the flow rate in gpm at $4.3 \mathrm{ft} / \mathrm{sec}$ ?
0.384 gallons $\times 4.3 \mathrm{FPS} \times 60 \mathrm{sec}(1 \mathrm{~min})=99.1 \mathrm{gpm}$

Now that the volumetric flow rate is known, all that is needed is an output frequency to determine the K-factor. Known values are:

| Frequency | $=$ | 700 Hz (By measurement) |
| :--- | :--- | :--- |
| Flow Rate | $=\quad 99.1 \mathrm{gpm}$ (By calculation) |  |

$700 \mathrm{~Hz} \times 60 \mathrm{sec}=42,000$ pulses per gallon

$$
\text { K-factor }=\frac{42,000 \text { pulses per } \mathrm{min}}{99.1 \mathrm{gpm}}=423.9 \text { pulses per gallon }
$$



## MODBUS INTERFACE

| Communications | Protocol | Modbus RTU |
| :--- | :--- | :--- |
|  | Interface | RS485, 2-wire and ground |
|  | Data transmission | Half-duplex |
|  | Baud rates | 9600 (default), 19200,38400,57600 and 115200 |
|  | Word length | 8-bits |
|  | Parity | None |
|  | Stop bits | 1 |
|  | Max. devices on network | 127 |
|  | Address range | $1 \ldots . .127$ |
|  | Cable | Shielded twisted pair with ground wire minimum 24 awg |
| Battery Life | 9600 Baud | Up to 6 years with Modbus enabled and no loop power |
|  | All other Baud rates | Up to 1 year with Modbus enabled and no loop power |

RS485 standards state that a daisy-chained topology is recommended with stubs being as short as possible (much shorter than the main bus length). Use a shielded twisted-pair cable no less than 24 awg for connecting devices on a RS485 network.
The BK2900 monitor is rated as a $1 / 8$ unit load device (input impedance equal to $96 \mathrm{k} \Omega$ ). The RS485 specification states it is capable of supporting 32 standard unit loads ( 1 standard unit load equals $12 \mathrm{k} \Omega$ ). In order to determine the maximum number of devices on a network, the user must identify the unit load rating of each device on the network.
The maximum common input voltage range of the BK2900 monitor is $-7 \ldots 10 \mathrm{~V}$. This differs from the RS485 standard of $-7 . . .12 \mathrm{~V}$. To make sure this range is achieved, the RS485 ground connection must be tied together in a daisy-chained fashion. The shield of the cable used should be tied to chassis or earth ground on only one end of the network. See Figure 24 and Figure 24 for an example configuration and description.

Use a termination resistor of $120 \Omega$ at the end of the bus.
A subset of the standard Modbus commands is implemented to provide access into the data and status of the BK2900 monitor. The Modbus commands and their limitations supported by the BK2900 monitor can be found in Table 3.

## IMPORTANT

A Modbus ground wire must be connected between the master and all other devices for proper operation.


| Label | Description |
| :---: | :---: |
| RS485 B( - ) | Inverting data signal |
| RS485 A $(+)$ | Non-inverting data signal |
| RS485 GND | Voltage reference for inverting and non-inverting signals |
| EARTH GND | Earth ground used for shield (only at one end of network) |

Figure 23: Daisy-chain wiring configuration example

| Command | Description |
| :---: | :---: |
| $\mathbf{0 1}$ | Read Coils |
| $\mathbf{0 3}{ }^{1}$ | Read Holding Registers |
| $\mathbf{0 5}$ | Force Single Coil |

Table 3: Modbus commands

| Type | Bits | Bytes | Modbus Registers |
| :---: | :---: | :---: | :---: |
| Long Integer | 32 | 4 | 2 |
| Single Precision IEEE754 | 32 | 4 | 2 |

Table 4: Available data formats

## Modbus Register / Word Ordering

The BK2900 monitor sends each byte of a 16-bit register in big-endian format. For example, the hex value ' 1234 ' is sent as ' 12 ' '34'. The BK2900 monitor provides for big-endian and little-endian word ordering when a master requests data. To accomplish this, the BK2900 monitor provides two register map spaces. See Table 5 and Table 6 for little-endian and big-endian register maps. Please note that both spaces provide the same data.

## Register Mappings

| Little-Endian |  |  |  |
| :---: | :---: | :---: | :---: |
| Data Component Name | Modbus Registers <br> Long Integer <br> Format | Single Precision <br> Floating Point <br> Format | Available Units |

Table 5: Modbus register map for 'little-endian' word order master devices
For reference: If the BK2900 Totalizer $=12345678$ hex
Register 40106 would contain 5678 hex (Word Low)
Register 40107 would contain 1234 hex (Word High)

| Big-Endian |  |  |  |
| :---: | :---: | :---: | :---: |
|  | Modbus Registers |  | Available Units |
| Data Component Name | Long Integer Format | Single Precision Floating Point Format |  |
| Spare | 40600... 40601 | 40700... 40701 | - |
| Flow Rate | 40602... 40603 | 40702... 40703 | Gallons, Liters, MGallons, Cubic Feet, Cubic Meters, Acre Feet, Oil Barrel, Liquid Barrel, Feet, Meters, Lb, Kg, BTU, MBTU, MMBTU, TON Per Second, Minute, Hour, Day |
| Spare | 40604... 40605 | 40704... 40705 |  |
| Positive Totalizer | 40606... 40607 | 40706... 40707 |  |
| Grand Total Totalizer | 40608... 40609 | 40708... 40709 |  |
| Battery Voltage | 40610... 40611 | 40710... 40711 | x.xx |
| Spare | 40612... 40613 | 40712... 40713 | - |

Table 6: Modbus register map for 'big-endian' word order master devices
For reference: If the BK2900 Totalizer $=12345678$ hex Register 40606 would contain 1234 hex (Word High) Register 40607 would contain 5678 hex (Word Low)

| Modbus Coil Description | Modbus Coil | Notes |  |
| :---: | :---: | :--- | :---: |
| Reset Running Totalizer | 1 | Forcing this coil ON will reset the running totalizer. After reset, the coil <br> automatically returns to the OFF state. |  |
| Reset Grand Totalizer | 2 | Forcing this coil ON will reset both the running totalizer and the grand <br> totalizer. After reset, the coil automatically returns to the OFF state. |  |
| - | $3 \ldots 8$ | Spares |  |
| Alarm Set point 1 | 9 | $0=$ Set point OFF, $1=$ Set point ON |  |
| Alarm Set point 2 | 10 | $0=$ Set point OFF, $1=$ Set point ON |  |
| - | $11 \ldots 16$ | Spares |  |
| Table 7:Modbus coil map |  |  |  |

## Opcode 01 - Read Coil Status

This opcode returns the state of the alarm coils. The following Coils are defined:

|  | Coil \# | Description |
| :---: | :---: | :---: |
|  | 9 | Alarm Set point 1 |
|  | 10 | Alarm Set point 2 |
|  | 11 and up | Spare |
| Table 8: Read coil status |  |  |
| Command: Reply: | $\begin{aligned} & <\text { addr }><01 \\ & <\text { <addr }><01 \end{aligned}$ |  |

## Opcode 03 - Read Holding Registers

This opcode returns the input holding registers, such as flow rate or totalizer.
NOTE: Each value must be requested individually. Return of a block of registers is not implemented at this time.
Example requesting flow rate in floating point format.
Command: <addr><03><00><C9><00><02><crc-16>
Reply: <addr><03><02><data><data><crc-16>

## Opcode 05 - Force Single Coil

This opcode sets the state of a single coil (digital output). The following Coil Registers are defined:

| Coil \# | Description |  |  |
| :---: | :---: | :---: | :---: |
| 1 | Reset Totalizer |  |  |
| 2 | Grand Totals |  |  |
| 3 and up | Spares |  |  |
| Table 9: Force single coil |  |  |  |

The transition of coil from 0 to 1 will initiate function. This bit is auto reset to 0 , so there is no need to set it to 0 after a totalizer reset command.

```
Command:
<addr><05><00><00><FF><00><crc-16>
Reply: <addr><05><00><00><FF><00><crc-16>
```


## SPECIFICATIONS



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## MOUNTING OPTIONS AND DIMENSIONS

## Meter Mount



| A | B | C | D | E | F | G dia |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 9.25 in. | 7.00 in. | 5.75 in. | 4.00 in. | 3.45 in. | 1.50 in. | $0.875 \mathrm{in}$. |
| $(235.0 \mathrm{~mm})$ | $(177.8 \mathrm{~mm})$ | $(146.0 \mathrm{~mm})$ | $(101.6 \mathrm{~mm})$ | $(87.6 \mathrm{~mm})$ | $(38.1 \mathrm{~mm})$ | $(22.2 \mathrm{~mm})$ |

## Remote Mount



| A | B | C | D | E | F | G | H | I dia |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 7.00 in. | 2.40 in. | 2.25 in. | 7.00 in. | 5.75 in. | 4.38 in. | 3.45 in. | 1.50 in. | 0.875 in. |
| $(177.8 \mathrm{~mm})$ | $(61.0 \mathrm{~mm})$ | $(57.2 \mathrm{~mm})$ | $(177.8 \mathrm{~mm})$ | $(146.0 \mathrm{~mm})$ | $(111.2 \mathrm{~mm}))$ | $(87.6 \mathrm{~mm})$ | $(38.1 \mathrm{~mm})$ | $(22.2 \mathrm{~mm})$ |

## Swivel Mount



| A | B | C | D | E | F | G dia |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $12.25 \mathrm{in}$. | $7.00 \mathrm{in}$. | 5.75 in. | 4.00 in. | 3.45 in. | 1.50 in. | $0.875 \mathrm{in}$. |
| $(311.2 \mathrm{~mm})$ | $(177.8 \mathrm{~mm})$ | $(146.0 \mathrm{~mm})$ | $(101.6 \mathrm{~mm})$ | $(87.6 \mathrm{~mm})$ | $(38.1 \mathrm{~mm})$ | $(22.2 \mathrm{~mm})$ |

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## WHO WE ARE

Kimray designs and manufactures oil and gas control products. Based on more than 65 years of pioneering product development, we provide products and services that are reliable, smart and inventive. We generate meaningful solutions by staying curious and engaging in customers' needs. Our product ideas are fueled by a deep desire to make a difference that is both personal and unique to the customer.

We have made it our life's work to provide products and services that are positively impactful. Through the years, this pursuit has built strong relationships. Our customers have known that buying from Kimray is about much more than the product. The relationships between Kimray representatives and our customers extend from before the sale through the life of the product. Those relationships, along with quality Kimray products, are the result of a company striving for excellence for our customers, our company and our community.

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